

A Level OCR Physics

Chapter 17 Oscillations

Question	Answers	Extra information	Mark	AO	Spec reference
1 (a) (i)	Period = $4.8 \text{ s}/3 = 1.6 \text{ s}$ $f = 1/T = 1/1.6 \text{ s} = 0.625 = 0.63 \text{ Hz}$	Evidence of use of graph to find T Frequency	1 1	2	5.3.1
(ii)	Maximum velocity = $\omega A = 2\pi f A$ $= 2 \times \pi \times 0.63 \times 0.02$ $= 0.0786 \text{ m s}^{-1} = 0.079 \text{ m s}^{-1}$	Evidence of use of frequency	1 1	1 2	5.3.1
(b)	Find the maximum gradient / gradient at $x = 0$		1	1	5.3.1
(c)	Sinusoidal/same number of waves / frequency / periodic time Inverted / a negative cosine graph Maximum acceleration = $\omega^2 A = (2\pi f)^2 A / = 0.308 \text{ m s}^{-2} = 0.31 \text{ m s}^{-2}$		1 1 1	2	5.3.1
(d)	Condition for SHM is that $a \propto -x$ So the graph of a is the same shape as that of x , but inverted		1	1	5.3.1
2 (a) (i)	Strategy: States that readings of T (as the dependent variable) will be measured for different values of independent variable, wire diameter, d . Clearly identifies at least 2 correct control variables, e.g. length/number of coils on spring, mass Make springs using wire of different diameters and measure the time period Repeat measurements, omit outliers, find mean	Identifies dependent, independent and 2 control variables Change d , measure T Repeat, take mean How to deal with outliers	1 1 1	1	5.3.1
(ii)	Measure the time for 10 oscillations and divide the time by 10	Allow other multiples of T	1	1	5.3.1

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(b)	Plausible reason e.g. the length of wire is the same so the volume/mass of the wire will vary with the area of the wire, which is proportional to d^2 .		1	3	5.3.1
(c)	Use the time period and mass to find the k : $T = 2\pi\sqrt{\frac{m}{k}}$ $k = \left(\frac{2\pi}{T}\right)^2 m$ Plot a graph of k (y -axis) against d^2 (x -axis), and if it is a straight line through the origin then the hypothesis is correct.	Evidence of use of equation to find k Correct axes identified Allow graph of T^2 vs. d^2	1 1	2	
3 (a)	$T = 2\pi\sqrt{\frac{m}{k}}$ Plot a graph of T against $\sqrt{\frac{l}{k}}$: the gradient = $2\pi\sqrt{m}$ Or Plot T^2 against $1/k$: gradient = $4\pi^2 m$ You need to collect values of time period and spring constant. Change k , measure time period, use at least 6 different springs Displace the trolley and measure the time for many oscillations with a stop clock, e.g. 5 and divide by 5 to find each time period Repeat measurements and find the average time period for each value of k .	Correctly identifies variables to plot, and how gradient relates to mass Indication of range of independent variable Accurate measurement of time Repeat measurements	1 1 1 1	1	5.3.1
(b)	Use the full reading on the stopwatch (to hundredths of a second) in measurements and calculation of the mean. Round up to one decimal place, and use uncertainty in using the	Use of full display on stopwatch until the calculation of final value.	1	1	5.3.1

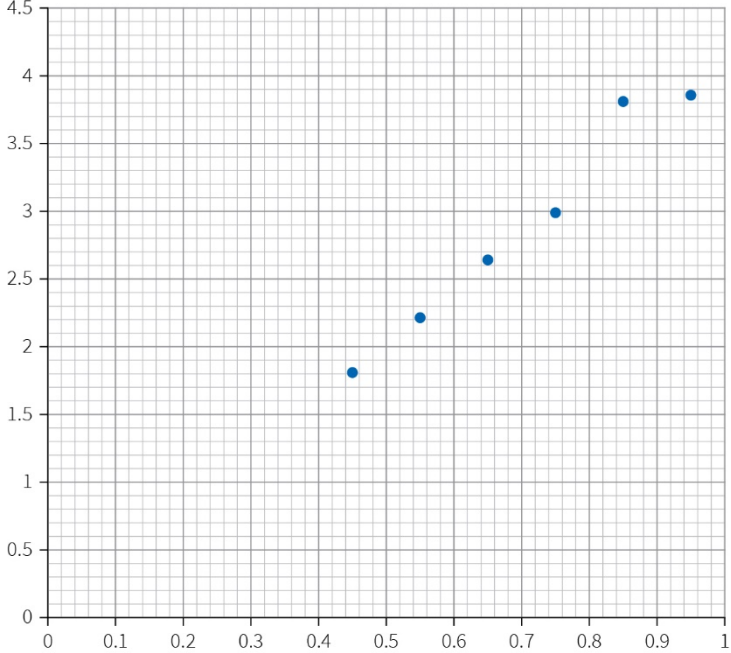
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	stopwatch = ± 0.2 s due to reaction time for both starting and stopping the stopwatch Giving a total uncertainty of ± 0.4 s	Estimation of reaction time Total uncertainty is double the reaction time	1 1		
(c)	Suitable method: Set up the light gate so that it is horizontal, and triggered by the mass when it goes through its equilibrium position. Attach a straw/light rod to the mass that breaks the beam as the mass goes through its equilibrium position. The measurement of T will be double the time measured by the light gate	Suitable practical arrangement Measurement of T that is accurate for the arrangement.	1 1	1	5.3.1
(d)	Each spring produces a restoring force of $-kx$, so the total restoring force = $-2kx$ $ma = -2kx$ compared to $ma = -kx$ so $\omega^2 = \frac{2k}{m}$, ω increases by $\sqrt{2}$ $T = \frac{2\pi}{\omega}$ so T is reduced by $\sqrt{2}$	Analysis to produce double the restoring force Use of $a = \omega^2 x$ Answer	1 1 1	2	5.3.1
4 (a) (i)	For each length: Allow the pendulum to swing 3 times (or more) Take the times recorded by the light gate and double them to find the time period Find the mean of all of the measurements.		1 1 1	1	5.3.1
(ii)	x -axis length, y -axis T^2 Line of best fit through (0, 0),	Both labels needed	1	2	5.3.1

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	 <p data-bbox="257 1066 1064 1098">Line of best fit ignoring anomalous result, with gradient of $4.0 \text{ s}^2 \text{ m}^{-1}$</p> $T = 2\pi \sqrt{\frac{l}{g}}$ $T^2 = 4\pi^2 \frac{l}{g} \text{ so graph of } T^2 \text{ vs } l \text{ has a gradient of } \frac{4\pi^2}{g}$ $g = \frac{4\pi^2}{\text{gradient}} = \frac{4\pi^2}{4.0} = 9.9 \text{ (9.87) m s}^{-2}$	<p data-bbox="1153 710 1310 742">Allow 3.9–4.1</p> <p data-bbox="1153 869 1601 933">Evidence of manipulation of equation Allow 9.62–10.1</p>	<p data-bbox="1713 710 1736 742">1</p> <p data-bbox="1713 869 1736 901">1</p> <p data-bbox="1713 949 1736 981">1</p>		
(iii)	Bigger – small angle approximation does not hold, bob may fall rather	Do not allow effect on g without	1	1	5.3.1

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	than swing, time period will be shorter than it should, g will be smaller than it should Smaller – amplitude does not affect time period, g not affected	explanation	1		
(b)	Systematic error in measurement of length		1	1	5.3.1
5 (a) (i)	The angle through which the pendulum is displaced should be small so that you can use the small angle approximation So that $T = 2\pi\sqrt{\frac{l}{g}}$, which is independent of mass		1 1	1	5.3.1
(ii)	$x = A \cos \omega t$ $A = 4.3 \times 10^{-2} \text{ m}$, $\omega = \frac{2\pi}{T} = \frac{2\pi}{1.8} = 3.5 \text{ rad s}^{-1}$ $x = 4.3 \times 10^{-2} \cos(3.5 t)$	Calculation of angular velocity Equation	1 1	2	5.3.1
(b) (i)	Maximum velocity = $\omega A = 3.5 \times 4.3 \times 10^{-2} = 0.15 \text{ m s}^{-1}$ Maximum kinetic energy = $\frac{1}{2}mv^2 = \frac{1}{2} \times 0.26 \times (0.15)^2 = 2.9 \times 10^{-3} \text{ J}$ Graph that is correct shape ($y = 1 - x^2$) Maximum labelled, x -axis from -3 cm to $+3 \text{ cm}$	Calculation of maximum kinetic energy	1 1 1	2	5.3.2

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(ii)	<p>Assuming the total energy is constant, the potential energy against time graph is x^2 graph So that the k.e. + p.e. at any position = total energy Or</p> $\text{Total energy} = \frac{1}{2}kA^2$ <p>So p.e = total energy – k.e.</p> $= \frac{1}{2}kA^2 - \frac{1}{2}mv^2$	<p>Assumption</p> <p>description</p>	<p>1</p> <p>1</p>	<p>1</p>	<p>5.3.2</p>
(c)	<p>The mass decreases, so kinetic energy decreases The line will not be symmetrical / the line will reach a lower value</p>		<p>1</p>	<p>2</p>	<p>5.3.2</p>
6 (a)	<p>Bathroom scales are compressed when you stand on them by an amount that is proportional to your weight/mass. In the ISS, both the scales and the astronaut are in free fall so the scales will not be compressed.</p>		<p>1</p> <p>1</p>	<p>2</p>	<p>3.2.1</p> <p>5.2.2</p>
(b) (i)	<p>The acceleration is proportional to the displacement, and in the opposite direction.</p>		<p>1</p>	<p>1</p>	<p>5.3.1</p>
(ii)	$T = 2\pi\sqrt{\frac{m}{k}}$			<p>2</p>	<p>5.3.1</p>

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	$k = m \left(\frac{2\pi}{T} \right)^2$ $= 72.65 \text{ kg} \left(\frac{2\pi}{2.103} \right)^2$ $= 648.5 \text{ N m}^{-1}$		1 1		
(iii)	$0.9 \times 72.65 \text{ kg} = 65.39 \text{ kg}$ $T = 2\pi \sqrt{\frac{61.76 \text{ kg}}{648.5 \text{ N m}^{-1}}}$ $= 1.995 \text{ s} = 2.0 \text{ s}$ <p>T is proportional to \sqrt{m} so as mass decreases so does periodic time</p>	Allow ecf from b) ii)	1 1 1	2	5.3.1
(iv)	Max displacement = amplitude which is proportion to energy Energy transferred to thermal store due to friction		1 1	3	5.3.1
(v)	No The mass depends on the time period, which is independent of amplitude		1 1	1	5.3.1
(c) (i)	The normal force between the outer edge of the station and the astronaut would 'simulate' gravity The normal force provides the centripetal force to keep the astronaut moving in a circle		2	3	5.2.2
(ii)	$g = v^2/r = 9.81 \text{ m s}^{-2}$ $v = \sqrt{9.81 \times 20}$ $= 14.0 \text{ m s}^{-1}$	Use of g to find v Or allow finding omega = 0.7 rad s^{-1}	1 1	3	5.2.2

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	$v = \frac{2\pi r}{T} = 2\pi r f$ $f = \frac{v}{2\pi} = \frac{14}{40\pi} = 0.11 \text{ Hz}$ <p>Revolutions per minute (rpm) = $0.11 \times 60 = 6.7 \text{ rpm}$</p>	<p>Correct value of f</p> <p>Correct rpm</p>	1		
7 (a) (i)	The acceleration is proportional to the displacement, and in the opposite direction/so as to restore the object to its equilibrium position		1	1	5.3.1
(ii)	<p>Volume of water displaced = $A x = 0.62 \text{ cm}^2 \times 1.5 \text{ cm} = 0.93 \text{ cm}^3$</p> <p>Mass of water = density of water \times volume = $0.93 \text{ cm}^3 \times 1 \text{ g cm}^{-3} = 0.93 \text{ g} = 9.3 \times 10^{-4} \text{ kg}$</p> <p>Weight = $mg = 9.3 \times 10^{-4} \text{ kg} \times 9.81 \text{ N kg}^{-1} = 9.12 \times 10^{-3} \text{ N}$</p>	<p>Correct use of equations for density and weight</p>	1 1	2	3.2.4 3.2.1
(iii)	The restoring force is proportional the distance that the tube is displaced from its equilibrium position: $F = -Ag\rho x$	Explanation of $F \propto x$	1	3	5.3.1
(iv)	<p>Acceleration = $F/m = 9.1 \times 10^{-3} \text{ N}/16 \times 10^{-3} \text{ kg}$</p> $a_{\text{max}} = 0.57 \text{ m s}^{-2}$ $a_{\text{max}} = \omega^2 A$ $= (2\pi f)^2 A$ $f = \sqrt{\frac{a_{\text{max}}}{A(2\pi)^2}}$	<p>Calculation of acceleration</p> <p>Use of $a_{\text{max}} = \omega^2 A$</p> <p>Alternatively, use $a_{\text{max}} = \omega^2 A$ to find ω, then use $T = 2\pi/\omega$</p> <p>Answer</p>	1 1 1	3	5.3.1

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	$f = \frac{0.57 \text{ ms}^{-1}}{\sqrt{0.015 \text{ m}(2\pi)^2}}$ $f = 0.98(1) \text{ Hz}$ $T = 1/f = 1/0.98 \text{ Hz} = 1.02 \text{ s}$				
(b) (i)	Restoring force $F = -Ag\rho x$ $a = -\frac{\text{Area} \times g \times \text{density}}{\text{mass of tube}} \cdot x$ $\omega^2 = \frac{\text{Area} \times g \times \text{density}}{\text{mass of tube}} = (2\pi f)^2 = \frac{(2\pi)^2}{T^2}$ $\text{density} \propto \frac{1}{T^2}$ A plot of density vs $1/\text{period}^2$ is a straight line	Derivation of value of ω^2 Manipulation to show time period Answer	1 1 1	3	5.3.1
(ii)	A series circuit with an LDR and a fixed resistor A cell/ battery and a voltmeter across either the LDR or resistor		1 1	1	4.3.1
8 (a) (i)	$k = F/x = 750 \text{ N}/2.5 \times 10^{-2} \text{ mm} = 30\,000 \text{ N m}^{-1}$		1	2	3.4.1
(ii)	$f = \frac{1}{2\pi} \sqrt{\frac{k}{m}} = \frac{1}{2\pi} \sqrt{\frac{30\,000}{1200}} = 0.080 \text{ Hz (0.796)}$ $T = 1/f = 1/0.70 = 1.2(6) \text{ s.}$		1 1	2	5.3.1
(iii)	If the car goes over a bump/speed bump it will displace the car from its equilibrium position		1	3	5.3.3
(iv)	$T = 2\pi \sqrt{\frac{m}{k}}$	Appropriate plot Gradient that matches plot.	1 1	2	5.3.1

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	Either: plot T^2 vs m , gradient = $\frac{4\pi^2}{k}$ Or: plot T vs \sqrt{m} , gradient = $2\pi\sqrt{\frac{l}{k}}$				
(b)	The oscillations are heavily/critically damped		1	2	5.3.3
(c) (i)	The engine vibration causes the door to vibrate and reflected vibrations set up standing waves in the door with nodes/ antinodes Where there are nodes there is little/no deformation, where there are antinodes there is maximum deformation		1 1	3	4.4.4
(ii)	The distance between the nodes is half a wavelength $\lambda = 2 \times 0.22 \text{ m} = 0.44 \text{ m}$ $v = f\lambda = 11\,300 \times 0.44 = 5000 (4972) \text{ m s}^{-1}$	Calculation of wavelength Answer to 2 significant figures	1 1	2	4.4.4