

# A Level AQA Physics

## 29 Discrete semi-conductor devices – answers

Question	Answers	Extra information	Mark	AO Spec reference
1.1	Gate, drain, and source all correctly labelled		1	3.13.1.1 AO1
1.2	Has very high input impedance/resistance No loading of logic gate output		1 1	3.13.1.1 AO1
1.3	MOSFET can easily become charged and switch on – the resistor prevents this/ keeps gate at 0 when no input		1	3.13.1.1 AO1
1.4	Diode An induced e.m.f. is created when a motor is switched on or off Without diode this would destroy MOSFET		1 1 1	3.13.1.1 AO1 AO2 × 2
2.1	2.2V is min p.d. across gate and source to form a channel between drain and source/gate voltage when the transistor is just switched off		1	3.13.1.1 AO1
2.2	Resistance increases as light intensity decreases Potential difference across the LDR increases Until threshold voltage achieved/current flows between drain and source and LED switched on		1 1 1	3.5.1.5 3.13.1.1 AO2
2.3	p.d. across $R = 6 - 2.2 = 3.8\text{V}$ $\frac{R}{3.8} = \frac{100\,000}{2.2}$ $R = 100\,000 \times \frac{3.8}{2.2}$ $R = 170\text{ k}\Omega$		1 1 1	3.5.1.5 3.13.1.1 AO2

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3.1	Max 4 marks from: <ul style="list-style-type: none"> <li>• Behaviour in forward bias direction same/same threshold voltage and then low resistance</li> <li>• Diode has large breakdown voltage/zener diodes have low breakdown voltages</li> <li>• Diode breaks if breakdown voltage exceeded/voltage across zener/zener voltage remains constant even when current exceeded</li> <li>• Reverse current of zener remains constant/at least 5 mA until breakdown voltage applied</li> </ul>	Must have similarities and differences for full marks	max 4	3.13.1.2 AO2
3.2	Correct symbol drawn Arrow pointing up		1 1	3.13.1.2 AO1
3.3	$P = VI$ $I = \frac{P}{V} = \frac{1.3}{4.3} = 0.30 \text{ A}$		1	3.5.1.4 3.13.1.2 AO1
3.4	$V = 9 - 4.3 = 4.7 \text{ V}$ $V = IR$ $R = \frac{4.7}{0.3} = 16 \Omega$		1 1	3.5.1.1 3.13.1.2 AO2
4.1	In parallel with zener diode so pd = 4.7 V $I = \frac{V}{R} = \frac{4.7}{440} = 0.011 \text{ A}$		1 1	3.13.1.2 3.5.1.1 AO2
4.2	p.d. = 10 - 4.7 = 5.3 V $I = \frac{V}{R} = \frac{5.3}{120} = 0.044 \text{ A}$		1 1	3.13.1.2 3.5.1.1 AO2
4.3	$I_Z = 0.044 - 0.011 = 0.033 \text{ A}$		1	3.13.1.2 3.5.1.4 AO1

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4.4	$P = IV = 0.033 \text{ A} \times 4.7 = 0.16 \text{ W} < 0.25 \text{ W}$ Use 250 mW zener diode		1 1	3.13.1.2 3.5.1.4 AO2
5.1	Reverse		1	3.13.1.3 AO1
5.2	Inverted parabola Peak at 850 nm Scale from 550 nm (min) to 1150 nm (max)	Ignore y-axis scale	1 1 1	3.13.1.3 AO1
5.3	Power = $I \times \text{Area} = 10 \times 1 \times 10^{-6} \text{ m}^2$ Current = sensitivity $\times$ power = $0.62 \times 10 \times 1 \times 10^{-6}$ Current = $6.2 \times 10^{-6} \text{ A}$		1 1 1	3.13.1.3 3.5.1.4 AO3
5.4	Max 4 marks from: <ul style="list-style-type: none"> <li>• Photodiode in series with a resistor and a power supply</li> <li>• <math>V_{\text{out}}</math> across the resistor</li> <li>• When it is dark, the current is negligible and there is no pd across resistor. No <math>V_{\text{out}}</math></li> <li>• When it is light, there is a current and hence a pd across the resistor – this is <math>V_{\text{out}}</math></li> <li>• Resistor chosen to provide suitable pd to activate alarm</li> </ul>	All marks can be awarded for suitably labelled diagram	max 4	3.13.1.3 AO3
6.1	Magnet placed on frame of set in line with hall effect sensor (allow vice versa) When the magnet is close to the sensor, voltage output is high/far from it, voltage output low Output fed to circuits for airbags/output amplified and input to circuits for airbags		1 1 1	3.13.1.4 AO1
6.2	$3.5 \times 10^{-4} \text{ T} = 0.35 \text{ mT}$ $V = 9 \times 0.35 = 3.2 \text{ mV}$ $0.014 \text{ T} = 14 \text{ mT}$ $V = 9 \times 14 = 126 \text{ mV}$		1 1	3.13.1.4 AO2

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6.3	0.065 mT $V = 0.59 \text{ mV}$ Too small to affect reading as this was max strength 20% of smallest value so would affect accuracy of output		1 1	3.13.1.4 AO2
7.1	As the magnet passes the sensor, it registers a voltage output The number of voltage outputs can be counted Using circumference of wheel, the distance can be measured/number of counts multiplied by distance of wheel		1 1 1	3.13.1.4 AO3
7.2	Distance = $\pi \times D = \pi \times 0.05 \text{ m}$ Speed = $\frac{\text{distance}}{\text{time}} = \frac{\pi \times 0.05 \text{ m}}{6.5 \times 10^{-3}} = 24 \text{ m s}^{-1}$		1 1	3.13.1.4 AO2
7.3	Have more magnets on disc/have a smaller radius disc	Allow any sensible suggestion here	1	3.13.1.4 AO3
8.1	Reverse		1	3.13.1.3 AO1
8.2	Leakage current when there is no/zero light intensity		1	3.13.1.3 AO1
8.3	Current = $0.6 \text{ A W}^{-1} \times 0.2 \times 10^{-3} \text{ W}$ Current = $1.2 \times 10^{-4} \text{ A}$		1	3.13.1.3 3.5.1.4 AO2
8.4	p.d. across $R = IR = 1.2 \times 10^{-4} \text{ A} \times 5000 \Omega = 0.6 \text{ V}$ $V_{\text{out}} = 9.0 - 0.6 = 8.4 \text{ V}$		1 1	3.13.1.3 3.5.1.1, 3.5.1.4 AO2

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### Skills box answers

Question	Answer
1	$I_{\max} = \frac{P}{V} = \frac{500 \times 10^{-3} \text{ W}}{5.1 \text{ V}} = 0.10 \text{ A}$
2	$P = IV = 10 \times 10^{-3} \text{ A} \times 2.7 \text{ V} = 0.03 \text{ W}$
3	$R_{\min} = \frac{(V_s - V_d)}{I_{\max}} = \frac{(12 - 10) \text{ V}}{100 \times 10^{-3} \text{ A}} = 20 \Omega$