A Level AQA Physics

## 12 Simple harmonic motion - answers

| Question | Answers | Extra information | Mark | AO | Spec reference |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 01.1 | $\begin{aligned} & \text { Period }=\frac{4.8 \mathrm{~s}}{3}=1.6 \mathrm{~s} \\ & f=\frac{1}{T}=\frac{1}{1.6 \mathrm{~s}}=0.625=0.63 \mathrm{~Hz} \end{aligned}$ | Evidence of use of graph to find $T$ Frequency | $\begin{aligned} & 1 \\ & 1 \end{aligned}$ | 2 | 3.6.1.1 |
| 01.2 | $\begin{aligned} \text { Maximum velocity }=\omega A & =2 \pi f A \\ & =2 \times 3.14 \times 0.63 \times 0.02 \\ & =0.0785 \mathrm{~m} \mathrm{~s}^{-1}=0.079 \mathrm{~m} \mathrm{~s}^{-1}=\left(7.9 \times 10^{-2} \mathrm{~m} \mathrm{~s}^{-1}\right) \end{aligned}$ | Evidence of use of frequency | 1 <br> 1 | $\begin{aligned} & 1 \\ & 2 \end{aligned}$ | 3.6.1.2 |
| 01.3 | Find the maximum gradient |  | 1 | 1 | 3.4.1.3 |
| 01.4 | Sinusoidal/same number of waves/frequency/periodic time Inverted/a negative cosine graph Maximum acceleration $=\omega^{2} A=(2 \pi f)^{2} A=0.308 \mathrm{~m} \mathrm{~s}^{-2}=0.31 \mathrm{~m} \mathrm{~s}^{-2}$ |  | $\begin{aligned} & 1 \\ & 1 \\ & 1 \end{aligned}$ | 2 | 3.6.1.2 |
| 01.5 | Condition for simple harmonic motion is that $a \propto-x$ So the graph of $a$ is the same shape as that of $x$, but inverted |  | 1 | 1 | 3.6.1.2 |
| 02.1 | Strategy: <br> States that readings of $T$ (as the dependent variable) will be measured for different values of independent variable, wire diameter, $d$. <br> Clearly identifies at least 2 correct control variables: length/number of coils on spring/ mass <br> Make springs using wire of different diameters and measure the time period Repeat measurements, omit outliers, find mean | Identifies dependent, independent and 2 control variables Change $d$, measure $T$ <br> Repeat, take mean How to deal with outliers | 1 <br> 1 <br> 1 1 | 1 | WS |
| 02.2 | Measure the time for 10 oscillations and divide the time by 10 |  | 1 | 2 | WS |
| 02.3 | Plausible reason, e.g. the length of wire is the same so the volume/mass of the wire will vary with the area of the wire, which is proportional to $d^{2}$ |  | 1 | 3 | 3.4.2.1 |

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| 02.4 | Use the time period and mass to find $k$ $\begin{aligned} & T=2 \pi \sqrt{\frac{m}{k}} \\ & k=\left(\frac{2 \pi}{T}\right)^{2} m \end{aligned}$ <br> Plot a graph of $k$ ( $y$-axis) against $d^{2}$ ( $x$-axis), and if it is a straight line then the hypothesis is correct | Evidence of use of equation to find $k$ <br> Correct axes identified | 1 <br> 1 | 3 | 3.6.1.3 |
| 03.1 | $T=2 \pi \sqrt{\frac{m}{k}}$ <br> Plot a graph of $T$ against $\sqrt{\frac{1}{k}}$ : the gradient $=2 \pi \sqrt{m}$ Or <br> Plot $T^{2}$ against $\frac{1}{k}$ : the gradient $=4 \pi^{2} m$ <br> Collect values of time period and spring constant <br> Change $k$, measure time period, use at least 6 different springs <br> Displace the trolley and measure the time for many oscillations with a stop <br> clock, e.g. 5, and divide by 5 to find each time period <br> Repeat measurements and find the average time period for each value of $k$ | Correctly identifies variables to plot, and how gradient relates to mass <br> Indication of range of independent variable Accurate measurement of time <br> Repeat measurements | 1 <br> 1 <br> 1 <br> 1 | 1 | 3.6.1.3 |
| 03.2 | Use the full reading on the stopwatch (to hundredths of a second) in measurements and calculation of the mean <br> Round up to one decimal place, and use uncertainty in using the stopwatch $= \pm 0.2 \mathrm{~s}$ due to reaction time for both starting and stopping the stopwatch Giving a total uncertainty of $\pm 0.4 \mathrm{~s}$ | Use of full display on stopwatch until the calculation of final value Estimation of reaction time Total uncertainty is double the reaction time | $1$ <br> 1 1 | 1 | WS |
| 03.3 | Suitable method: <br> Set up the light gate so that it is horizontal and triggered by the mass when it goes through its equilibrium position <br> Attach a straw/light rod to the mass that breaks the beam as the mass goes through its equilibrium position <br> The measurement of $T$ will be double the time measured by the light gate | Suitable practical arrangement <br> Measurement of $T$ that is accurate for the arrangement | 1 1 | 1 | 3.6.1.2 |

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| 03.4 | Each spring produces a restoring force of $-k x$, so the total restoring force $=-2 k x$ <br> $m a=-2 k x$ compared to $m a=-k x$ <br> so $\omega^{2}=\frac{2 k}{m}, \omega$ increases by $\sqrt{2}$ <br> $T=\frac{2 \pi}{\omega}$ so $T$ is reduced by $\frac{1}{\sqrt{2}}$ | Analysis to produce double the restoring force <br> Use of $a=\omega^{2} x$ <br> Answer | 1 <br> 1 <br> 1 | 2 | 3.6.1.2 |
| 04.1 | For each length: <br> Allow the pendulum to swing 3 times (or more) <br> Take the times recorded by the light gate and double them to find the time period <br> Find the mean of all of the measurements |  | $\begin{aligned} & 1 \\ & 1 \\ & 1 \end{aligned}$ | 1 | 3.6.1.3 |

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| 04.2 |  |  |  |  |  |  |  |  |  |  | 1 | 2 | 3.6.1.3 |
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|  | $x$-axis length, $y$-axis $T^{2}$ <br> Line of best fit through ( 0,0 ) <br> Line of best fit ignoring anomalous result, with gradient of $\frac{4.0 \mathrm{~s}^{2}}{1 \mathrm{~m}}$ $T=2 \pi \sqrt{\frac{l}{g}}$ <br> $T^{2}=4 \pi^{2} \frac{l}{g}$ so graph of $T^{2}$ versus $l$ has a gradient of $\frac{4 \pi^{2}}{g}$ $g=\frac{4 \pi^{2}}{\text { gradient }}=\frac{4 \pi^{2}}{4.0}=9.9(9.87) \mathrm{m} \mathrm{~s}^{-2}$ <br> Both labels needed of equation <br> Allow 9.62-10.1 |  |  |  |  |  |  |  |  |  |  |  |  |
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| 04.3 | Bigger - small angle approximation does not hold, bob may fall rather than swing, time period will be shorter than it should be $g$ will be smaller than it should be <br> Smaller - amplitude does not affect time period, $g$ not affected | Do not allow effect on $g$ without explanation | 1 <br> 1 | 1 | 3.6.1.3 |
| 04.4 | Systematic error in measurement of length |  | 1 | 2 | 3.4.2.2 |
| 05.1 | The angle through which the pendulum is displaced should be small so that you can use the small angle approximation <br> So that $T=2 \pi \sqrt{\frac{l}{g}}$ pendulum equation, which is independent of mass |  | 1 <br> 1 | 1 | 3.6.1.3 |
| 05.2 | $\begin{aligned} & x=A \cos \omega t \\ & A=3.2 \times 10^{-2} \mathrm{~m}, \omega=\frac{2 \pi}{T}=\frac{2 \pi}{1.4}=4.5 \mathrm{rad} \mathrm{~s}^{-1} \\ & x=3.2 \times 10^{-2} \cos (4.5 t) \end{aligned}$ | Calculation of angular velocity <br> Equation | 1 <br> 1 | 2 | 3.6.1.2 |
| 05.3 | Maximum velocity $=\omega A=4.5 \times 0.032=0.14 \mathrm{~m} \mathrm{~s}^{-1}$ <br> Maximum kinetic energy $=\frac{1}{2} m v^{2}=\frac{1}{2} \times 0.26 \times(0.14)^{2}=2.7 \times 10^{-3} \mathrm{~J}$ <br> Graph that is correct shape ( $y=1-x^{2}$ ) <br> Maximum labelled, $x$-axis from -3.2 cm to +3.2 cm | Calculation of maximum kinetic energy | 1 $\begin{aligned} & 1 \\ & 1 \end{aligned}$ | 2 | 3.6.1.2 |

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| :---: | :---: | :---: | :---: | :---: | :---: |
| 05.4 | Assuming the total energy is constant, the potential energy versus time graph is $x^{2}$ graph So that the kinetic energy + potential energy at any position = total energy Or $\text { Total energy }=\frac{1}{2} k A^{2}$ <br> So potential energy = total energy - kinetic energy $=\frac{1}{2} k A^{2}-\frac{1}{2} m v^{2}$ | Assumption <br> description | $1$ $1$ | 1 | 3.6.1.3 |
| 05.5 | The mass decreases, so kinetic energy decreases The line will not be symmetrical/the line will reach a lower value |  | 1 | 2 | 3.6.1.3 |
| 06.1 | Bathroom scales are compressed when you stand on them by an amount that is proportional to your weight/mass <br> In the International Space Station, both the scales and the astronaut are in free fall so the scales will not be compressed / gravitational field strength is lower |  | 1 <br> 1 | 2 | 3.4.1.1 |
| 06.2 | $\begin{aligned} T & =2 \pi \sqrt{\frac{m}{k}} \\ k & =m\left(\frac{2 \pi}{T}\right)^{2} \\ & =68.62 \mathrm{~kg} \times\left(\frac{2 \pi}{2.084}\right)^{2} \\ & =623.8 \mathrm{Nm}^{-1} \end{aligned}$ |  | 1 <br> 1 | 2 | 3.6.1.3 |
| 06.3 | $\begin{aligned} 0.9 & \times 68.62 \mathrm{~kg}=61.76 \mathrm{~kg} \\ T & =2 \pi \sqrt{\frac{61.76 \mathrm{~kg}}{623.8 \mathrm{Nm}^{-1}}} \\ & =1.977 \mathrm{~s} \end{aligned}$ <br> ( $T$ is proportional to $\sqrt{m}$ so as mass decreases so does periodic time) |  | $1$ | 2 | 3.6.1.3 |

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| 06.4 | Max displacement = amplitude, which is proportion to energy Energy transferred to thermal store due to friction |  | $\begin{aligned} & 1 \\ & 1 \end{aligned}$ | 3 | 3.6.1.3 |
| 06.5 | No <br> The mass depends on the time period, which is independent of amplitude |  | $\begin{aligned} & 1 \\ & 1 \end{aligned}$ | 1 | 3.6.1.3 |
| 07.1 | $\begin{aligned} & \text { Volume of water displaced }=A \times x=0.75 \mathrm{~cm}^{2} \times 1.0 \mathrm{~cm}=0.75 \mathrm{~cm}^{3} \\ & \text { Mass of water }=\text { density of water } \times \text { volume }=0.75 \mathrm{~cm}^{3} \times 1 \mathrm{~g} \mathrm{~cm}^{-3} \\ & =0.75 \mathrm{~g}=7.5 \times 10^{-4} \mathrm{~kg} \\ & \text { Weight }=m g=7.5 \times 10^{-4} \mathrm{~kg} \times 9.81 \mathrm{Nkg}^{-1}=7.357 . . \times 10^{-3} \mathrm{~N} \end{aligned}$ | Correct use of equations for density and weight | 2 | 2 | 3.4.2.1 |
| 07.2 | The restoring force is proportional to the distance that the tube is displaced from its equilibrium position ORF $=-A g \rho x$ | Explanation of $F \propto x$ | 1 | 3 | 3.6.1.2 |
| 07.3 | $\begin{aligned} & \text { Acceleration }=\frac{F}{m}=\frac{7.4 \times 10^{-3} \mathrm{~N}}{12 \times 10^{-3} \mathrm{~kg}} \\ & a_{\max }=0.61 \mathrm{~m} \mathrm{~s}^{-2} \\ & a_{\max }=\omega^{2} A=(2 \pi f)^{2} A \\ & f=\sqrt{\frac{a_{\max }}{A(2 \pi)^{2}}} \\ & f=\sqrt{\frac{0.61 \mathrm{~m} \mathrm{~s}^{-1}}{0.01 \mathrm{~m}(2 \pi)^{2}}} \\ & f=1.2(4) \mathrm{Hz} \\ & T=\frac{1}{f}=\frac{1}{1.24 \mathrm{~Hz}}=0.80 \mathrm{~s} \end{aligned}$ | Calculation of acceleration <br> Use of $a_{\text {max }}=\omega^{2} A$ <br> Alternatively, use $a_{\text {max }}=\omega^{2} A$ to find $\omega$, then use $T=\frac{2 \pi}{\omega}$ <br> Answer | 1 <br> 1 <br> 1 | 3 | 3.6.1.2 |

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| :---: | :---: | :---: | :---: | :---: | :---: |
| 07.4 | Restoring force $F=-A g \rho x$ $\begin{aligned} & a=-\frac{\text { area } \times g \times \text { density }}{\text { mass of tube }} \times x \\ & \omega^{2}=\frac{\text { area } \times g \times \text { density }}{\text { mass of tube }}=(2 \pi f)^{2}=\frac{2 \pi^{2}}{T^{2}} \\ & \text { density } \propto \frac{1}{T^{2}} \end{aligned}$ <br> A plot of density versus $\frac{1}{(\text { period })^{2}}$ is a straight line | Derivation of value of $\omega^{2}$ <br> Manipulation to show time period <br> Answer | 1 <br> 1 <br> 1 | 3 | 3.4.2.1 |
| 07.5 | A series circuit with an LDR and a fixed resistor A cell/battery and a voltmeter across either the LDR or resistor |  | $\begin{aligned} & 1 \\ & 1 \end{aligned}$ | 1 | 3.5.1.5 |
| 08.1 | $k=\frac{F}{x}=\frac{700 \mathrm{~N}}{3.0 \times 10^{-2} \mathrm{~mm}}=23000 \mathrm{~N} \mathrm{~m}^{-1}$ |  | 1 | 2 | 3.4.2.1 |
| 08.2 | $\begin{aligned} & f=\frac{1}{2 \pi} \sqrt{\frac{k}{m}}=\frac{1}{2 \pi} \sqrt{\frac{23000}{1200}}=0.70 \mathrm{~Hz} \\ & T=\frac{1}{f}=\frac{1}{0.70}=1.4(2) \mathrm{s} \end{aligned}$ |  | $\begin{aligned} & 1 \\ & 1 \end{aligned}$ | 2 | 3.6.1.3 |
| 08.3 | If the car goes over a bump/speed bump, it will displace the car from its equilibrium position |  | 1 | 3 | 3.6.1.2 |
| 08.4 | $T=2 \pi \sqrt{\frac{m}{k}}$ <br> Either: plot $T^{2}$ versus $m$, gradient $=\frac{4 \pi^{2}}{k}$ Or: plot $T$ versus $\sqrt{m}$, gradient $=2 \pi \sqrt{\frac{1}{k}}$ | Appropriate plot <br> Gradient that matches plot | $\begin{aligned} & 1 \\ & 1 \end{aligned}$ | 1 | 3.6.1.3 |
| 08.5 | The oscillations are heavily/critically damped |  | 1 | 2 | 3.6.1.4 |

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Skills box answers
Question Answer

1
Use a fiducial marker (such as a pin) stuck at the equilibrium point of the mass.
Reduce parallax by observing oscillation at the same level as the fiducial marker/mass.
Use small displacements of the mass so that the mass hanger doesn't 'jump' at the minimum displacement of the oscillation.
Include a measurement of reaction time in the measured time period.

